Contents

FI	gure	S	X	
Ta	ables		xiii	
Se	eries	Editors' Introduction	XV	
Pr	efac	e	xvii	
I	Int:	roduction to DSGE Modeling and Bayes ference	- 1	
1	DSGE Modeling			
	1.1	A Small-Scale New Keynesian DSGE Model	3	
		Other DSGE Models Considered in This Book	11	
2	Turning a DSGE Model into a Bayesian Model 1			
		Solving a (Linearized) DSGE Model	16	
		The Likelihood Function	19	
	2.3	Priors	22	
3	A Crash Course in Bayesian Inference			
		The Posterior of a Linear Gaussian Model	31	
		Bayesian Inference and Decision Making	35	
		A Non-Gaussian Posterior	43	
	3.4	Importance Sampling	46	
	3.5	Metropolis-Hastings Algorithms	52	

II	Es	timation of Linearized DSGE Models	63
4		ropolis-Hastings Algorithms for DSGE Models A Benchmark Algorithm	6 5
	4.2	The RWMH-V Algorithm at Work	69
	4.3	Challenges Due to Irregular Posteriors	77
	4.4	Alternative MH Samplers	8]
	4.5	Comparing the Accuracy of MH Algorithms	87
	4.6	Evaluation of the Marginal Data Density	93
5	Sequential Monte Carlo Methods		
	5.1	A Generic SMC Algorithm	101
	5.2	Further Details of the SMC Algorithm	109
	5.3	SMC for the Small-Scale DSGE Model	125
6	Thr	ee Applications	130
	6.1	A Model with Correlated Shocks	131
	6.2	The Smets-Wouters Model with a Diffuse Prior	141
	6.3	The Leeper-Plante-Traum Fiscal Policy Model	150
Ш	F		
111		stimation of Nonlinear DSGE Models	161
7		n Linear to Nonlinear DSGE Models	161163
	Fron		
	Fron 7.1	n Linear to Nonlinear DSGE Models	163
7	From 7.1 7.2	n Linear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions	163 164
7	From 7.1 7.2 Part	n Linear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions Adding Nonlinear Features to DSGE Models	163 164 167
7	From 7.1 7.2 Part 8.1	n Linear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions Adding Nonlinear Features to DSGE Models icle Filters	163 164 167
7	From 7.1 7.2 Part 8.1 8.2	n Linear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions Adding Nonlinear Features to DSGE Models icle Filters The Bootstrap Particle Filter	163 164 167 171 173
7	From 7.1 7.2 Part 8.1 8.2 8.3	n Linear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions Adding Nonlinear Features to DSGE Models icle Filters The Bootstrap Particle Filter A Generic Particle Filter	163 164 167 171 173 182
7	From 7.1 7.2 Part 8.1 8.2 8.3 8.4	n Linear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions Adding Nonlinear Features to DSGE Models icle Filters The Bootstrap Particle Filter A Generic Particle Filter Adapting the Generic Filter	163 164 167 171 173 182 185
7	From 7.1 7.2 Part 8.1 8.2 8.3 8.4 8.5	n Linear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions Adding Nonlinear Features to DSGE Models icle Filters The Bootstrap Particle Filter A Generic Particle Filter Adapting the Generic Filter Additional Implementation Issues	163 164 167 171 173 182 185 191
7	From 7.1 7.2 Part 8.1 8.2 8.3 8.4 8.5 8.6	n Linear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions Adding Nonlinear Features to DSGE Models icle Filters The Bootstrap Particle Filter A Generic Particle Filter Adapting the Generic Filter Additional Implementation Issues Adapting s_{t-1} Draws Application to the Small-Scale DSGE Model	163 164 167 171 173 182 185 191 198
7	From 7.1 7.2 Part 8.1 8.2 8.3 8.4 8.5 8.6 8.7	n Linear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions Adding Nonlinear Features to DSGE Models icle Filters The Bootstrap Particle Filter A Generic Particle Filter Adapting the Generic Filter Additional Implementation Issues Adapting s_{t-1} Draws	163 164 167 171 173 182 185 191 198 204
7	From 7.1 7.2 Part 8.1 8.2 8.3 8.4 8.5 8.6 8.7 8.8	n Linear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions Adding Nonlinear Features to DSGE Models icle Filters The Bootstrap Particle Filter A Generic Particle Filter Adapting the Generic Filter Additional Implementation Issues Adapting s_{t-1} Draws Application to the Small-Scale DSGE Model Application to the SW Model	163 164 167 171 173 182 185 191 198 204 212
7	From 7.1 7.2 Part 8.1 8.2 8.3 8.4 8.5 8.6 8.7 8.8 Com	Nonlinear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions Adding Nonlinear Features to DSGE Models icle Filters The Bootstrap Particle Filter A Generic Particle Filter Adapting the Generic Filter Additional Implementation Issues Adapting s_{t-1} Draws Application to the Small-Scale DSGE Model Application to the SW Model Computational Considerations	163 164 167 171 173 182 185 191 198 204 212 216
7	From 7.1 7.2 Part 8.1 8.2 8.3 8.4 8.5 8.6 8.7 8.8 Com 9.1	Nonlinear to Nonlinear DSGE Models Nonlinear DSGE Model Solutions Adding Nonlinear Features to DSGE Models icle Filters The Bootstrap Particle Filter A Generic Particle Filter Adapting the Generic Filter Additional Implementation Issues Adapting s_{t-1} Draws Application to the Small-Scale DSGE Model Application to the SW Model Computational Considerations bining Particle Filters with MH Samplers	163 164 167 171 173 182 185 191 198 204 212 216

	9.4	Computational Considerations	229
10	10.1	bining Particle Filters with SMC Samplers An SMC^2 Algorithm Application to the Small-Scale DSGE Model Computational Considerations	231 231 237 239
Ap	pend	ix	241
A	A.1	el Descriptions Smets-Wouters Model Leeper-Plante-Traum Fiscal Policy Model	241 241 247
В	B.1 B.2	Sources Small-Scale New Keynesian DSGE Model Smets-Wouters Model Leeper-Plante-Traum Fiscal Policy Model	249249249251
Bibliography			257
Index			